

# A Preconditioning Strategy Applicable To A Family Of IDR( $s$ ) Methods For Reduction Of Computational Cost

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We consider to solve a large non-singular linear system of equations,

$$Ax = b$$

where  $A$  is a given nonsymmetric coefficient ( $N \times N$ )-matrix, and  $x$ ,  $b$  are a solution vector and right-hand side vector of order  $N$ , respectively. Krylov subspace of order  $n$  is spanned by

$$K_n(A; r_0) := \text{span}\{r_0, Ar_0, \dots, A^{n-1}r_0\},$$

where  $r_0 (= b - Ax_0)$  is an initial residual vector. As known well, Krylov subspace methods are effective iterative methods for solving large linear systems of equations. Recently, IDR( $s$ ) method based on IDR (Induced Dimension Reduction) Theorem[4] was proposed by P. Sonneveld and M.B. van Gijzen[2]. Moreover, generalization and extension of IDR Theorem was studied by G. Sleijpen[1] and M. Tanio[3].

In a family of IDR( $s$ ) methods, computation of multiplication of transpose matrix  $P^T$  and a vector is needed commonly at every iteration. Here  $P$  is a dense matrix in  $R^{N \times s}$ [2]. Computational cost of multiplication of  $P^T$  and a vector dominates in the algorithm of several IDR( $s$ ) methods, and the more parameter  $s$ , the more computational cost. Therefore it is an issue how we construct a structure of dense matrix  $P$ .

In this article, as one of preconditioning techniques, we propose a structure of a dense matrix  $P$  composed with divided  $s$  column vectors of size  $\lfloor N/s \rfloor \times 1$ . Here  $\lfloor \cdot \rfloor$  denotes the so-called Gauss symbol. We refer to this partially dense matrix as Slim Dense (abbreviated as **S\_Dense**) matrix. As a result of adoption of this preconditioning strategy, computational cost of a family of IDR( $s$ ) methods can be reduced.

Table 1 shows the convergence of GIDR( $s$ ,  $L = 2$ ) method for dense and S\_Dense matrices  $P$ . In this Table, " $s_{opt}$ ." means optimum parameter  $s$  in view of CPU time. "*ave. time*" means average CPU time per one iteration in milli-seconds. "ratio" means ratio of CPU time of GIDR( $s$ ,  $L = 2$ ) method using S\_Dense matrix to that of GIDR( $s$ ,  $L = 2$ ) method using dense matrices  $P$ . The bold figure means the least CPU time of GIDR( $s$ ,  $L = 2$ ) method of dense and S\_Dense matrices  $P$  for each matrix. From Table 1, we can see that the proposed preconditioning strategy using S\_Dense matrix  $P$  is very effective for improvement of efficiency of GIDR( $s$ ,  $L$ ) method.

## References

- [1] Sleijpen, G.L.G., Sonneveld, P., van Gijzen, M.B. : Bi-CGSTAB as an Induced Dimension Reduction Method, Depart. of Applied Math. Anal., TR08-07(2008), Delft University of Technology.

Table 1: Convergence of GIDR( $s, L = 2$ ) method of dense and S\_Dense matrices  $P$ .

matrix	ave. nnz	structure of $P$	$s_{opt}$	itr.	time [sec.]	ratio	ave. time [msec.]
2*language	2* 3.047	dense	1	44	1.19	1.0	27.068
		S_Dense	3	40	<b>1.07</b>	0.901	26.825
2*epb3	2* 5.479	dense	2	2748	11.25	1.0	4.097
		S_Dense	5	2424	<b>9.91</b>	0.881	4.090
2*memplus	2* 7.104	dense	4	230	0.26	1.0	1.130
		S_Dense	7	192	<b>0.22</b>	0.842	1.141
2*add20	2* 7.231	dense	3	152	0.027	1.0	0.178
		S_Dense	6	140	<b>0.025</b>	0.926	0.179
2*matrix_9	2*20.512	dense	6	1960	25.30	1.0	12.910
		S_Dense	6	1932	<b>22.36</b>	0.884	11.576
2*xenon2	2*24.556	dense	4	1450	32.36	1.0	22.318
		S_Dense	5	1356	<b>28.95</b>	0.895	21.350
2*poisson3Db	2*27.737	dense	4	380	6.35	1.0	16.721
		S_Dense	5	360	<b>5.81</b>	0.915	16.144
2*sme3Dc	2*73.344	dense	7	3456	6.76	1.0	17.870
		S_Dense	8	3366	<b>58.32</b>	0.944	17.327
2*raefsky2	2*90.550	dense	8	378	0.35	1.0	0.931
		S_Dense	8	378	<b>0.33</b>	0.957	0.892

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- [4] Wesseling, P., Sonneveld, P.: Numerical Experiments with a Multiple Grid-and a Preconditioned Lanczos Type Methods, Lecture Notes in Math., Springer, No.771, pp.543-562, 1980.